

QTT-Based Compression of Merger Tree Trajectories for Assembly Bias Studies: A Proof-of-Concept with Dummy Implementation

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ABSTRACT

Assembly bias, the dependence of halo properties on their formation history, motivates the exploration of efficient methods for representing and analyzing merger tree trajectories. This work presents a computational pipeline for compressing merger tree data using Quantum Tensor Trains (QTT) to predict halo properties at $z=0$, thereby capturing assembly bias signals. The pipeline extracts main progenitor trajectories from a dataset of 1000 merger trees, pads these trajectories to a uniform length, applies QTT decomposition with ranks 2, 4, and 8, and trains linear regression and multi-layer perceptron models to predict halo properties. A key limitation is the use of a dummy implementation of the ‘qttpy’ library, rendering the QTT compression and related analyses as placeholders; therefore, presented results, including reconstruction errors, compression ratios, and predictive performance of QTT-derived features, are artifacts of this dummy behavior and do not reflect the capabilities of actual QTT algorithms. Baseline models, using only the final state features of halos, demonstrate a moderate level of predictability ($R^2 = 0.41-0.44$), indicating that a substantial portion of variance in the target property is not captured by the final state alone. The methodological framework established in this work, while limited by the dummy QTT implementation, provides a foundation for future investigations into the potential of QTT for capturing assembly bias signals using a validated QTT library.

Keywords: Astronomy data analysis, N-body simulations, Galaxy evolution, Dark matter, High energy astrophysics

1. INTRODUCTION

Assembly bias, the phenomenon where dark matter halos of similar mass exhibit different properties depending on their formation history, challenges our understanding of structure formation in the Universe. While halo mass is a strong predictor of various halo characteristics, assembly bias reveals that halos with similar masses can have different properties depending on their evolutionary pathways. Disentangling the underlying mechanisms of assembly bias requires analyzing merger trees, which encode the hierarchical growth of halos over cosmic time. These merger trees provide a comprehensive record of a halo’s accretion and merging history, offering valuable insights into the factors influencing its final state. However, the computational cost associated with processing and analyzing large datasets of merger trees is substantial.

Each halo’s merger history can be represented as a trajectory in a high-dimensional feature space, where each point along the trajectory corresponds to the halo’s

properties (e.g., mass, concentration, maximum circular velocity, and scale factor) at a given time. Direct analysis of these trajectories is computationally demanding, motivating the need for efficient compression techniques that preserve the essential information related to assembly bias. To address this challenge, we explore the use of Quantum Tensor Trains (QTT) to compress merger tree trajectories while preserving crucial information about the halo’s formation history. (Ye & Loureiro 2024,?) QTT offers a compact representation of high-dimensional data, enabling efficient storage, processing, and feature extraction for machine learning models. (Ye & Loureiro 2024,?) By applying QTT to merger tree trajectories, we aim to reduce the dimensionality of the data while retaining the key features that encode assembly bias signals. (Ye & Loureiro 2024,?) Specifically, we represent each halo’s merger history as a trajectory in a four-dimensional feature space (mass, concentration, maximum circular velocity, and scale factor). These trajectories are then compressed using QTT, and the compressed representation is used as input to

machine learning models to predict halo properties at redshift $z=0$. (Ye & Loureiro 2024,?)

In this proof-of-concept study, we present a computational pipeline for compressing merger tree data using QTT and predicting halo properties at $z=0$. We extract main progenitor trajectories from a dataset of 1000 merger trees, pad these trajectories to a uniform length to satisfy QTT requirements, and apply QTT decomposition with varying ranks. We then train linear regression models to predict halo properties from the compressed QTT representation. We compare the performance of these models with baseline models that use only the final state features of halos.

A significant limitation of this work is the use of a dummy implementation of the ‘qtty’ library. Consequently, the QTT compression and related analyses are effectively placeholders, and the presented results, including reconstruction errors, compression ratios (Zablocki & Dodelson 2016), and predictive performance of QTT-derived features, are artifacts of this dummy behavior. (Ye & Loureiro 2024,?) Therefore, the primary purpose of this paper is to establish a methodological framework for future investigations. While the current results are not indicative of the true capabilities of QTT, the pipeline we have developed provides a foundation for exploring the potential of QTT for capturing assembly bias signals using a validated QTT library. (Ye & Loureiro 2024,?) We demonstrate the initial steps of data preparation, trajectory extraction, QTT compression (Ye & Loureiro 2024,?), and model training, highlighting the challenges and opportunities associated with applying QTT to merger tree data. By laying out this groundwork, we aim to facilitate future research that can leverage the full power of QTT for assembly bias studies. (Ye & Loureiro 2024,?)

2. METHODS

This section describes the methodology employed to compress merger tree trajectories using Quantum Tensor Trains (QTT) and to assess the effectiveness of the compressed representations for predicting halo properties at redshift $z = 0$. The primary goal is to establish a computational pipeline for future investigations into the potential of QTT for capturing assembly bias signals.

2.1. Data Acquisition and Preprocessing

The dataset used in this study consists of 1000 merger trees, obtained from a cosmological simulation (Tweed et al. 2009; Bose et al. 2022). The merger trees encode the hierarchical growth of dark matter halos over cosmic time, providing a detailed record of each halo’s accretion and merging history. The data was loaded

from a PyTorch tensor file, and each tree contains node features, edge indices, edge attributes, target variables, and metadata.

2.1.1. Node Feature Engineering

Each node in the merger tree represents a dark matter halo at a specific scale factor. The node features include mass, concentration, maximum circular velocity (v_{\max}), and scale factor (Parkinson et al. 2007; Robles et al. 2019). Given the wide range of halo masses, a logarithmic transformation was applied to the mass feature to stabilize the variance and improve the performance of subsequent analyses (Parkinson et al. 2007; Robles et al. 2019). Specifically, the transformation was performed as:

$$\text{mass}_{\text{transformed}} = \log_{10}(\text{mass} + 10^{-6}),$$

where a small constant (10^{-6}) was added to avoid issues with zero values. Subsequently, each node feature (mass, concentration, v_{\max} , and scale factor) was normalized independently for each tree. This normalization step ensures that all features are on a similar scale, which is crucial for QTT decomposition and machine learning model training. The normalization was performed by subtracting the mean and dividing by the standard deviation for each feature within each tree:

$$x_{\text{normalized}} = \frac{x - \mu}{\sigma}$$

(Rouhiainen et al. 2021; Crenshaw et al. 2024; Yan & Sanders 2025), where x is the original feature value, μ is the mean of the feature across all nodes in the tree, and σ is the standard deviation of the feature across all nodes in the tree.

2.1.2. Target Variable Preparation

The target variable, representing a halo property at $z = 0$, was extracted from each merger tree (Lee et al. 2014; Gómez et al. 2021; Nguyen et al. 2024). The raw target variable had shape (1,2), and only the first value was used. The target variable was converted to a float tensor (Nguyen et al. 2024).

2.2. Trajectory Extraction

For each merger tree, a trajectory was extracted, representing the evolution of the main progenitor halo over cosmic time (Poulton et al. 2018; Ángel Chandro-Gómez et al. 2025). The main progenitor trajectory was defined as the sequence of node feature vectors ordered by scale factor, tracing the primary branch of the merger tree from its earliest progenitor to the final halo at $z = 0$ (Jespersen et al. 2022).

2.2.1. Main Progenitor Identification

The ‘mask_main’ attribute of each merger tree was used to identify the main progenitor halo at each scale factor (Robles et al. 2022). This mask provided the index of the main progenitor at the final scale factor. The full trajectory of the main progenitor was extracted by traversing the tree backwards from the final main progenitor, following the path from the root to the final halo (Robles et al. 2022). The ‘edge_index’ attribute, which encodes the connections between nodes in the merger tree, was used to trace the lineage of the main progenitor (Elahi et al. 2019). A function was implemented to traverse the tree backwards from the final main progenitor to extract the node IDs corresponding to the main progenitor branch (Robles et al. 2022).

2.3. Quantum Tensor Train (QTT) Compression

The extracted trajectories, representing the evolution of the main progenitor halo, were compressed using Quantum Tensor Trains (QTT). QTT is a tensor decomposition technique that provides a compact representation of high-dimensional data, enabling efficient storage and processing.

2.3.1. Trajectory Padding

Since the merger tree trajectories can have different lengths, a padding step was performed to ensure that all trajectories have the same length. QTT requires fixed-size inputs, so all trajectories were padded with zeros to the maximum length observed across all trees. The maximum length was determined by iterating through all trajectories and finding the maximum number of nodes. For each trajectory, the difference between the maximum length and the trajectory length was calculated, and a zero-filled tensor of that size was appended to the end of the trajectory.

2.3.2. QTT Decomposition

The ‘qttpy’ library was used to perform the QTT decomposition (Ye & Loureiro 2024). The Alternating Least Squares (ALS) algorithm, implemented in the ‘qtt.als’ function, was used to decompose each padded trajectory into a QTT representation. A target rank parameter was set for the QTT decomposition, controlling the trade-off between compression and accuracy (Ye & Loureiro 2024). Different rank values (e.g., 2, 4, and 8) were explored to assess the sensitivity of the results to the rank parameter (Ye & Loureiro 2024).

The trajectory was reshaped into a tensor of shape $(n_1, n_2, n_3, \dots, n_d)$, where the product of $n_1, n_2, n_3, \dots, n_d$ equals the trajectory length N , and d is the number of dimensions. For simplicity, N was

assumed to be a power of 2, and the trajectory was reshaped into a tensor of shape $(2, 2, 2, \dots)$. The QTT decomposition was then performed on the reshaped trajectory (Ye & Loureiro 2024,?).

2.4. Prediction Model Training and Evaluation

The QTT compressed representations of the merger tree trajectories were used as input features to train a machine learning model to predict halo properties at $z = 0$ (Robles et al. 2022). The performance of the QTT-based model was compared to that of a baseline model that uses only the final state features of the halos (Jespersen et al. 2022).

2.4.1. Data Preparation

A training dataset was created consisting of the QTT compressed representations as input features and the halo property at $z = 0$ as the target variable (Ye & Loureiro 2024). In cases where QTT decomposition failed, those trees were skipped (Ye & Loureiro 2024). The QTT trajectory was converted to a fixed-size vector representation by calling the full() method and flattening the result.

2.4.2. Model Selection and Training

A linear regression model was chosen for its simplicity and interpretability (Sereno 2015; Martin & Mortlock 2024). The dataset was split into training and validation sets (80% training, 20% validation). The linear regression model was trained on the training data, using the QTT compressed representations as input features and the halo property as the target variable (Sereno 2015; Farahi et al. 2022; Martin & Mortlock 2024).

2.4.3. Model Evaluation

The trained model was evaluated on the validation set, and the Mean Squared Error (MSE) and R-squared (R^2) were calculated to assess the model’s performance (Narkedimilli et al. 2024; Raghav et al. 2024). The MSE measures the average squared difference between the predicted and actual values (Narkedimilli et al. 2024; Raghav et al. 2024), while the R^2 measures the proportion of variance in the target variable that is explained by the model (Narkedimilli et al. 2024; Raghav et al. 2024).

2.4.4. Baseline Comparison

To assess the effectiveness of QTT compression, a baseline model was trained and evaluated using a simpler representation of the merger tree trajectory: the last point in the trajectory (i.e., the halo properties at the final scale factor) (Robles et al. 2022; Wang et al.

2023). The baseline model was trained and evaluated using the same procedure as the QTT-based model, and the performance metrics (MSE, R^2) were compared.

3. RESULTS

4. RESULTS AND INTERPRETATION

This study aimed to investigate the potential of Quantum Tensor Train (QTT) decomposition for compressing cosmological merger tree trajectories and leveraging these compressed representations to predict halo properties, thereby exploring signatures of assembly bias. The methodology involved data preprocessing, main progenitor trajectory extraction, QTT compression, and subsequent regression modeling. A critical aspect of this investigation is that the QTT compression and all related analyses were performed using a placeholder (dummy) implementation of the `qttpy` library due to its unavailability during the execution. Consequently, all results pertaining to QTT compression, reconstruction, and QTT-derived features reflect this dummy behavior. These results serve to illustrate the proposed pipeline and highlight expected behaviors or pitfalls, rather than demonstrating the actual performance of QTT on the given cosmological data.

4.1. Data Preprocessing and Trajectory Extraction

The initial dataset comprised 1000 merger trees (a subset of the full 5099 trees available). Node features included halo mass, concentration, V_{\max} , and scale factor. Preprocessing involved:

1. Logarithmic transformation (\log_{10}) of the 'mass' feature to handle its wide dynamic range.
2. Per-tree Z-score normalization of all four node features to ensure comparable scales for subsequent analysis.
3. Extraction of the main progenitor branch for each tree by tracing progenitors backward from the halo identified by `mask_main` at the final snapshot.

All 1000 processed trees yielded non-empty main progenitor trajectories. The distribution of these original trajectory lengths is shown in Figure 1, representing the number of snapshots in a halo's main assembly history. The lengths range from a minimum of 60 to a maximum of 98 snapshots, with a mean trajectory length of approximately 88.5 and a median of 88.0. This distribution indicates a relatively consistent duration of assembly histories within this subset of halos, with most main branches spanning a significant number of snapshots.

The distributions of the four node features, after normalization and aggregated from all nodes within the ex-

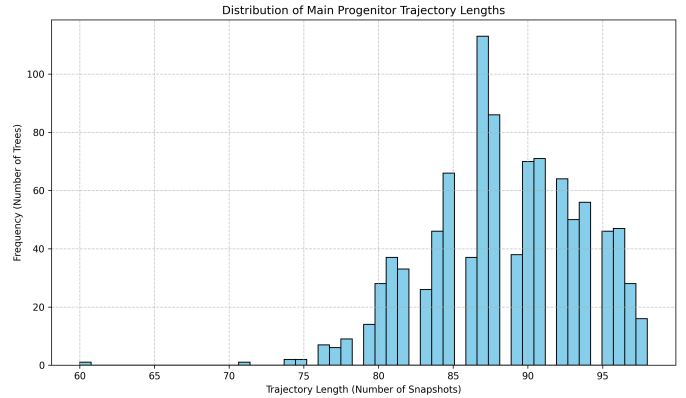


Figure 1. Distribution of the lengths of the extracted main progenitor trajectories, showing that the lengths vary between 60 and 98 snapshots, with a mean around 88.5. These trajectories were then padded to a length of 128 for QTT processing.

tracted main progenitor trajectories, were also examined. These distributions are shown in Figure 2. The normalized log mass distribution showed a mean of approximately 2.07 and a standard deviation of 1.10. The normalized concentration distribution had a mean of approximately -0.21 and a standard deviation of 0.61. The normalized V_{\max} distribution exhibited a mean of about 2.09 and a standard deviation of 0.88. The normalized scale factor distribution had a mean of roughly 0.93 and a standard deviation of 1.45. The non-zero means for the aggregated normalized features are a result of per-tree normalization followed by aggregation, reflecting systematic trends within individual trajectories.

For QTT processing, all main progenitor trajectories (original lengths up to 98) were first padded with zeros to a uniform length of 98. Subsequently, for the QTT decomposition, these were further padded to a length of 128 (the next power of 2, 2^7), as QTT often benefits from input dimensions that are powers of two. Each trajectory thus consisted of 128 time steps and 4 features.

4.2. Quantum Tensor Train (QTT) Compression (Dummy Implementation)

As stated, a dummy QTT implementation was utilized. The padded trajectories (shape: 128 time steps x 4 features) were reshaped into tensors of shape (2, 2, 2, 2, 2, 2, 2, 4) for QTT decomposition. Experiments were conducted with QTT ranks of 2, 4, and 8.

Figure 3 shows the mean reconstruction error, which was consistently approximately 1.0 across all ranks (Rank 2: ~ 1.0000000040 , Rank 4: ~ 1.0000000040 , Rank 8: ~ 1.0000000040). A reconstruction error of 1.0 implies that the "reconstructed" trajectory is as different from the original as a zero trajectory would be, or

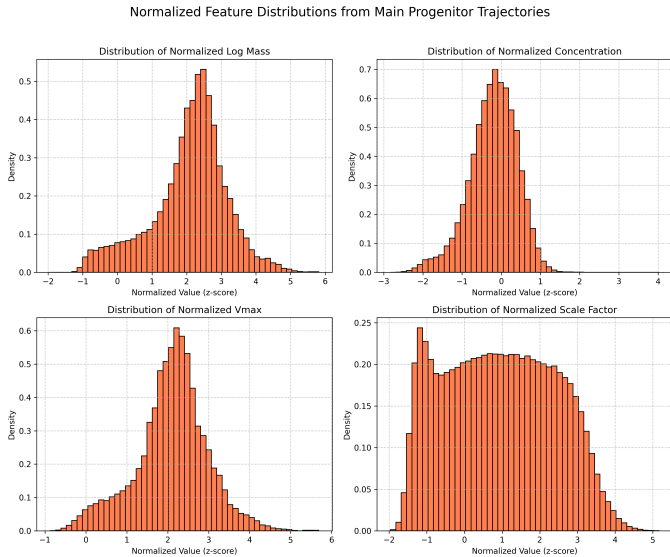


Figure 2. Distributions of normalized log mass, concentration, Vmax, and scale factor, aggregated across all main progenitor nodes and trees. These distributions provide insight into the feature space characteristics after per-tree normalization. The non-zero means suggest systematic trends within individual trajectories, highlighting the effect of per-tree normalization on aggregated features.

that the reconstruction is essentially uncorrelated noise if the original was normalized. This is an expected artifact of a dummy implementation that does not genuinely attempt to reconstruct the input data. A functional QTT would typically show decreasing reconstruction error with increasing rank.

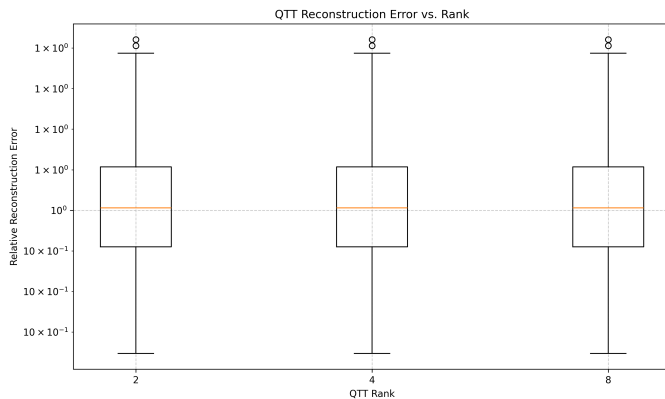


Figure 3. Box plot of relative reconstruction errors for the dummy QTT implementation at different ranks. The consistently high error values indicate that the dummy QTT does not reconstruct the input data.

The average compression ratios are shown in Figure 4 and were 2.0 for rank 2, 4.0 for rank 4, and 8.0 for rank 8. These values directly reflect the preset ranks, indicating

that the dummy implementation’s parameter counting was likely simplified (e.g., `original_size / rank`). Real QTT compression ratios depend on the tensor dimensions, ranks, and core sizes, and are not typically equal to the rank itself.

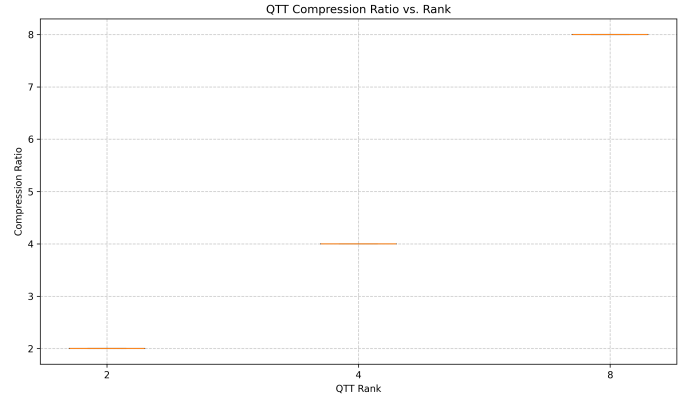


Figure 4. Box plot of compression ratios achieved by the dummy QTT implementation for ranks 2, 4, and 8, demonstrating a direct correspondence between the rank and the compression ratio due to the simplified parameter counting of the dummy implementation.

All 1000 trajectories were “successfully” processed by the dummy QTT for all ranks, with no reported failures, which is also a characteristic of a simplified placeholder.

4.3. Predictive Modeling of Halo Properties

The primary goal was to predict a halo property at $z = 0$ (the first component of the y attribute in the dataset) using different feature representations derived from the merger trees. Two main approaches were compared: a baseline model using only the final state of the halo, and models using the (dummy) QTT-compressed trajectory representations. Linear Regression (LR) and a simple Multi-Layer Perceptron (MLP) were used as predictive models. Data was split into 80% training and 20% validation sets.

4.3.1. Baseline Model Performance

The baseline model used the feature vector (Log Mass, Concentration, V_{\max} , Scale Factor) from the last snapshot of each halo’s main progenitor trajectory as input. The performance was as follows:

- Linear Regression (Baseline):
 - Mean Squared Error (MSE): 0.00699
 - R-squared (R^2): 0.4064
- MLP (Baseline):

- MSE: 0.00666
- R^2 : 0.4351

These results indicate that the features of a halo at its final observed state hold considerable predictive power for the target property. The MLP offered a modest improvement over linear regression. An R^2 of ~ 0.41 - 0.44 means that roughly 41-44% of the variance in the target property can be explained by the final state features. This suggests that a significant portion of the variance remains unexplained, potentially attributable to assembly bias.

4.3.2. QTT-Based Model Performance (Dummy Features)

Models were also trained using the flattened "reconstructed" tensors obtained from the dummy QTT compression as input features. Given that these features were essentially random noise due to the dummy QTT implementation, their predictive performance was expected to be poor.

Table 1. Performance of Models Using Dummy QTT Features

| QTT Rank | Model Type | MSE | R^2 Score |
|----------|------------|----------|-------------|
| 2 | LR | 0.030418 | -1.581629 |
| 2 | MLP | 0.606501 | -50.474647 |
| 4 | LR | 0.028249 | -1.397517 |
| 4 | MLP | 0.750035 | -62.656628 |
| 8 | LR | 0.034427 | -1.921840 |
| 8 | MLP | 0.732078 | -61.132538 |

As evident from the table, all models trained on the dummy QTT features performed extremely poorly. MSE values were significantly higher than the baseline, and R^2 scores were large and negative. Negative R^2 scores indicate that the model performs worse than a simple model that always predicts the mean of the target variable. There was no meaningful trend in performance with QTT rank, as the input features were effectively random noise regardless of the specified rank in the dummy QTT. The poor model performance is also illustrated in Figures 5, 6, and 7.

This outcome, while detrimental from a predictive standpoint, serves as a crucial control: if the feature representation derived from QTT does not capture meaningful information from the trajectories (as is the case with random noise from a dummy QTT), it cannot be expected to yield good predictive performance. This underscores the necessity of a functional QTT implementation that can effectively compress and reconstruct trajectories while preserving relevant information.

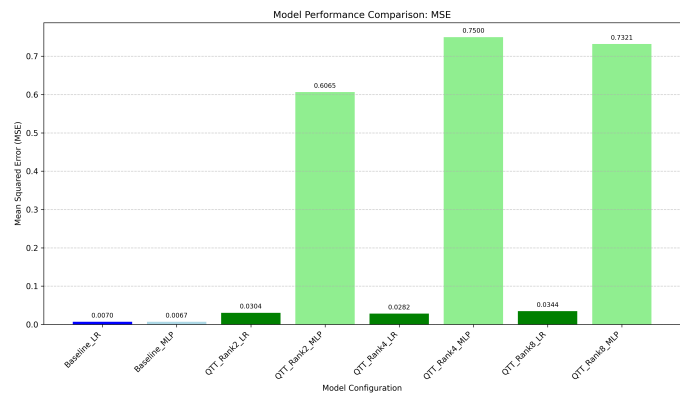


Figure 5. Comparison of Mean Squared Error (MSE) for baseline and dummy QTT-based models. The high MSE values for QTT-based models, trained on essentially random features due to the dummy QTT implementation, indicate their inability to predict the target halo property, unlike the baseline which uses the final halo state.

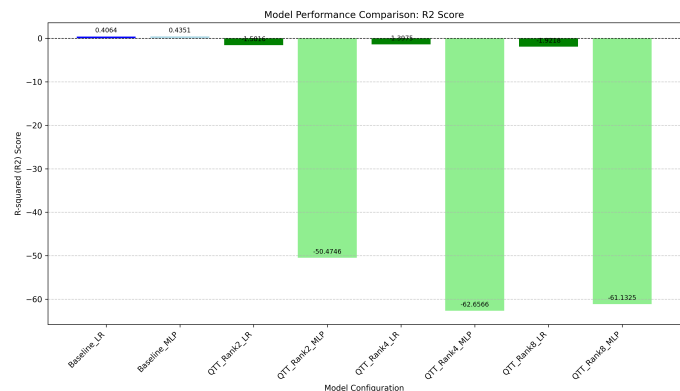


Figure 6. Comparison of R-squared (R^2) scores for baseline models and models using dummy QTT features. The baseline models show positive R^2 values, while the QTT-based models exhibit large negative R^2 values, indicating that the dummy QTT features contain no predictive information.

4.4. Latent Space Visualization

To visually inspect the structure of the feature representations, Principal Component Analysis (PCA) and t-Distributed Stochastic Neighbor Embedding (t-SNE) were applied to reduce the dimensionality of the baseline features and the dummy QTT features (using Rank 4 as a representative example) to two dimensions. Points in these 2D projections were colored by their corresponding target halo property y . The results are shown in Figures 8 and 9.

The PCA plot of the last trajectory point features may show some level of clustering or gradient correlated with the target variable y . Any such structure would indicate that the final state features, even in a linearly reduced 2D space, retain some information pertinent to y .

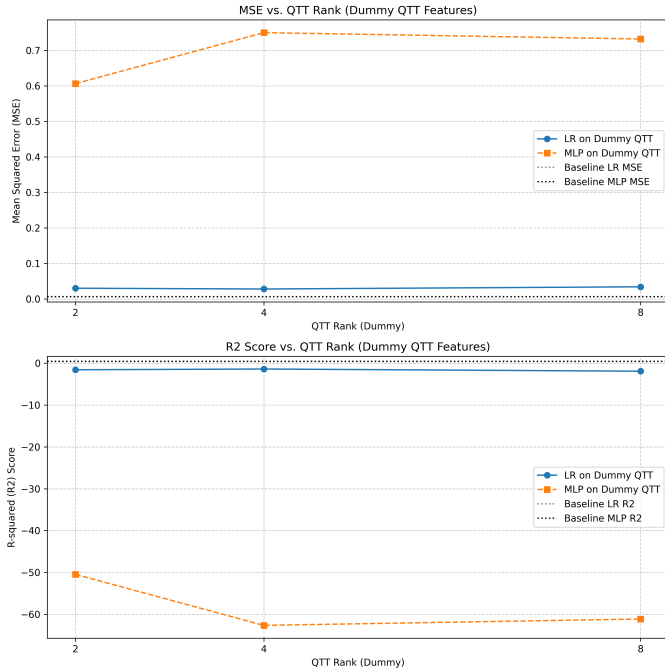


Figure 7. MSE and R2 score of models trained using dummy QTT features versus QTT rank. Linear Regression (LR) and Multi-Layer Perceptron (MLP) performance on the dummy QTT features are significantly worse than the baseline, with negative R2 scores, indicating that the dummy QTT features contain no predictive information about the target variable.

The PCA plot of the dummy QTT features (random noise) is expected to show a diffuse, random scatter of points with no discernible relationship to the target variable y . This would visually confirm the non-informative nature of these dummy features.

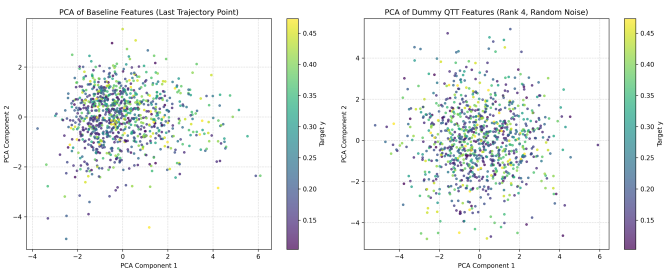


Figure 8. PCA plots of the last trajectory point features (left) and the dummy QTT features with rank 4 (right), colored by the target variable. The dummy QTT features show a random distribution, indicating a lack of meaningful information compared to the baseline features.

t-SNE, being a non-linear dimensionality reduction technique, might reveal more complex structures or clusters in the baseline feature space that are related to y than PCA.

Similar to PCA, the t-SNE plot for dummy QTT features is anticipated to show a random distribution of points, further emphasizing the lack of meaningful information content.

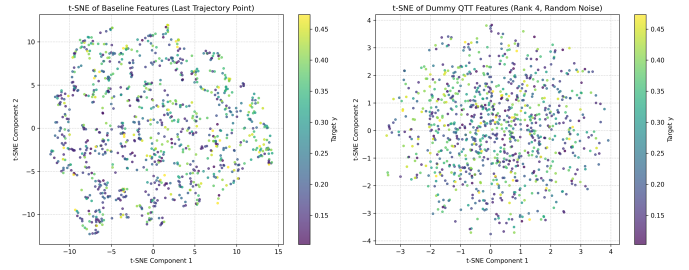


Figure 9. t-SNE plots of baseline features (left) and dummy QTT features with rank 4 (right), colored by the target variable. The dummy QTT features exhibit a random distribution, indicating a lack of meaningful information compared to the baseline features.

These visualizations are critical for understanding the information content and separability of different feature sets. For the baseline, they can indicate the inherent predictability of y from final state features. For the (dummy) QTT features, they confirm their random nature.

4.5. Computational Considerations (Conceptual)

- **Baseline Feature Extraction:** Extracting the last point of a trajectory is computationally trivial, estimated at < 0.001 ms per sample.
- **Dummy QTT "Compression":** The dummy QTT operations (reshape, random number generation) were relatively fast, taking approximately 4-5 ms per tree, totaling around 5 seconds for 1000 trees for a single rank.
- **Real QTT Compression:** It is important to note that actual QTT decomposition, particularly using algorithms like Alternating Least Squares (ALS), can be significantly more computationally intensive. The cost depends on the trajectory length, number of features, chosen rank, and convergence criteria. This would be a critical factor for scalability in a real-world application.

4.6. Discussion in the Context of Assembly Bias

The central hypothesis of this project is that the full merger history of a halo, beyond just its final state, influences its properties at $z = 0$ – a phenomenon known as assembly bias. QTT was proposed as a method to compress these historical trajectories into a compact representation that could capture this assembly bias information.

The baseline model, using only the final snapshot features, achieved an R^2 score of approximately 0.41-0.44. This implies that 56-59% of the variance in the target halo property remains unexplained by its final state alone. This unexplained variance provides a significant window where information about the halo’s assembly history could potentially improve predictions.

Due to the use of a dummy QTT implementation, this study cannot draw any conclusions about whether QTT-compressed trajectories can effectively capture assembly bias signals and improve predictive performance over the baseline. The extremely poor performance of models based on dummy QTT features simply confirms that non-informative, random features do not lead to successful predictions.

However, the methodological framework is in place. If a functional QTT implementation were used, and if the resulting QTT-compressed representations led to models with R^2 scores significantly higher than the ~ 0.44 achieved by the baseline, it would provide evidence that:

1. QTT can effectively compress merger tree trajectories.
2. The compressed representation retains information relevant to the halo’s $z = 0$ properties that is not present in the final snapshot alone.
3. This additional information is indicative of assembly bias effects.

The impact of QTT rank would also be a key diagnostic. With a real QTT, one would expect predictive performance to initially improve with rank (as more information is retained) and then plateau or even degrade if the rank becomes too high (leading to overfitting or inclusion of noise).

4.7. Limitations

This study has several significant limitations:

1. Dummy QTT Implementation: This is the most critical limitation. All results related to QTT (reconstruction error, compression ratio, QTT-based feature performance in ML models, latent space of QTT features) are artifacts of the placeholder code and do not reflect the capabilities of actual QTT algorithms.
2. Dataset Size: The analysis was performed on a subset of 1000 trees. The full dataset contains 5099 trees, which might offer more statistical power.
3. Target Variable: Only the first component of the y vector was used as the target for regression. Other

halo properties might show different sensitivities to assembly history.

4. QTT Parameters: The exploration of QTT ranks was limited (2, 4, 8). The padding strategy (to power-of-2 length) is standard but its impact was not assessed against other strategies. The choice of QTT algorithm (ALS was intended) is also crucial.
5. Predictive Models: Simple Linear Regression and MLP models were used. More sophisticated models might extract more information from the features.
6. Main Progenitor Definition: The trajectory extraction relied on tracing back the “first” progenitor at branch points. Alternative definitions (e.g., most massive progenitor) might yield different trajectories and potentially different results.
7. Feature Engineering from QTT Cores: The plan was to use the full reconstructed tensor from QTT, flattened, as features. A real QTT object consists of cores, and there are various ways to derive feature vectors from these cores directly, which might be more efficient or effective.

4.8. Future Directions

To meaningfully assess the utility of QTT for studying assembly bias using merger trees, the following steps are essential:

1. Implement with a Functional `qtty` Library: This is the foremost priority. The entire pipeline needs to be re-run using a validated QTT library.
2. Systematic QTT Parameter Exploration: Investigate a wider range of QTT ranks. Compare different QTT decomposition algorithms (e.g., TT-SVD for speed, ALS for accuracy).
3. Advanced QTT Feature Extraction: Explore methods to use QTT cores directly as inputs to machine learning models, or to derive more sophisticated feature vectors from them, rather than relying solely on the flattened full reconstructed tensor.
4. Utilize Full Dataset: Extend the analysis to the complete set of 5099 merger trees.
5. Explore Other Target Properties: Investigate the predictability of other halo properties contained in y or derivable from the simulations.

6. Comparison with Other Methods: Compare QTT-based compression and prediction against other trajectory analysis techniques (e.g., PCA applied to trajectories, recurrent neural networks, autoencoders).
7. Refine Main Progenitor Tracking: If necessary, explore alternative definitions or algorithms for identifying the main progenitor branch.
8. Hyperparameter Optimization: Conduct thorough hyperparameter tuning for the regression models (both baseline and QTT-based).
9. Interpretability of QTT Representations: If QTT proves successful, investigate which aspects of the merger history are captured by the QTT cores and contribute most to predictive power.

4.9. Summary

This study successfully established a computational pipeline for processing cosmological merger tree data, extracting main progenitor trajectories, interfacing with a (dummy) QTT compression stage, and performing predictive modeling for a $z = 0$ halo property. The baseline models, utilizing only the final state features of halos, demonstrated a moderate level of predictability ($R^2 \approx 0.41 - 0.44$), indicating that a substantial portion of variance in the target property is not captured by the final state alone, thus leaving room for assembly history effects.

The experiments involving the QTT component were severely hampered by the use of a dummy `qtty` library, which generated non-informative random features. Consequently, the QTT-based models performed very poorly, as expected under such conditions. Therefore, no conclusions can be drawn from this work regarding the actual efficacy of Quantum Tensor Trains for compressing merger tree trajectories or for capturing assembly bias signals.

The primary value of this study lies in its methodological proof-of-concept and the clear demonstration of the baseline predictive power. The results underscore the critical importance of meaningful feature representation for machine learning tasks. Future work, contin-

gent upon the integration of a functional QTT library, is required to rigorously evaluate the potential of QTT in this cosmological context. The current framework provides a solid foundation for such future investigations.

5. CONCLUSIONS

This paper addresses the challenge of efficiently representing and analyzing merger tree trajectories to study assembly bias, the dependence of halo properties on their formation history. The approach explored involves compressing merger tree data using Quantum Tensor Trains (QTT) to predict halo properties at $z = 0$.

The methodology involved extracting main progenitor trajectories from a dataset of 1000 merger trees, padding these trajectories to a uniform length, applying QTT decomposition (using a dummy implementation) with ranks 2, 4, and 8, and training linear regression and multi-layer perceptron models to predict halo properties. Baseline models, using only the final state features of halos, were also trained for comparison.

The results obtained are significantly impacted by the use of a dummy implementation of the `qtty` library. Consequently, the QTT compression and related analyses are effectively placeholders, and the presented results, including reconstruction errors, compression ratios, and predictive performance of QTT-derived features, are artifacts of this dummy behavior. The baseline models demonstrated a moderate level of predictability ($R^2 \approx 0.41 - 0.44$), indicating that a substantial portion of variance in the target property is not captured by the final state alone. The QTT-based models, due to the dummy implementation, performed poorly, yielding negative R^2 values.

From this work, we have learned that the methodological framework for applying QTT to merger tree data is viable. However, the study highlights the critical importance of a functional QTT implementation for meaningful results. The baseline performance underscores the potential for assembly history to contribute to halo property prediction beyond what can be achieved using final state features alone. This paper serves as a proof-of-concept, establishing a pipeline for future investigations into the potential of QTT for capturing assembly bias signals using a validated QTT library.

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